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Revised December 2013

www.barkeraircraft.com/files/AOA_Display.pdf

This months project

Angle of Attack Indicator.

–Dave Barker EAA Chapter 79

This device is really just a simple weather vane with the axis mounted horizontally to indicate relative wind in the vertical direction as opposed to azimuth for a weather vane on the barn. Why AOA (Angle Of Attack) ? Because it can tell you what the aircraft is really doing compared to the typical variable incidence of the Pitot tube rigidly mounted under the wing. The pivoting vane of the AOA detector always flies directly into the relative wind. The angle it makes with the attack angle of the wing can be measured and provides accurate flight status in high pucker- factor maneuvers such as short take off and landing attitudes. The pick-up makes use of a linear Hall effect sensor. This is a device that outputs a voltage proportional to the strength of a magnetic field. The Vane of the AOA carries a small permanent magnet that rotates with the Vane relative to the Hall sense device located on the Delrin mount sleeve. The output voltage is used to drive a panel mounted 10-segment multicolor bargraph display. The display LED's change position and color from Green to Yellow to Red as the angle of attack increases.



The AOA display board requires minimal panel space, but should be mounted high on the panel to stay within your peripheral field of vision while looking outside.



All LEDs ON (Not the normal display)

The hardest part of this project is deciding where to mount the vane assembly. And then routing the connecting cable through the wing to the sensor. The sensor vane needs to be located in the undisturbed airflow away from prop blast and wing Empennage effects.

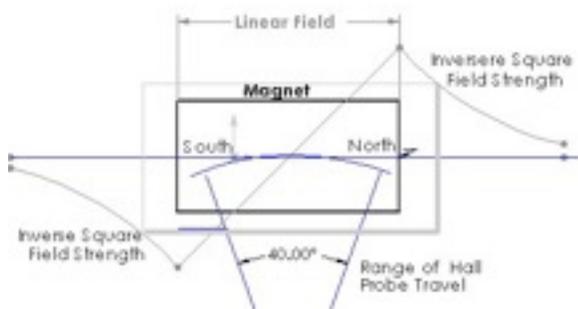


Display and Sensor

In many aircraft mounting parallel to the side of the Pitot tube structure is a good choice. My plane has a typical heated Pitot tube structure and I build a Delrin ring carrier for the Hall sensor and pivot that slides on the Pitot tube and positions the vane parallel and slightly behind the Pitot intake port.

The vane and fin itself can be formed from plastic. I used a piece of Delrin rod equipped with an aluminum fin. For the production version I used a 4-40 SHCS and a 5/16" brass sleeve for a pivot shaft. The vane carries a small 0.375" long cylindrical permanent magnetic mounted in the inboard face of the vane about 1/4" ahead of the pivot shaft. The North to South side face of magnet rolls about the pivot parallel to the hall sensor face. By keeping the arc travel

within the physical length of the magnet we can achieve a linear position voltage output from the Hall sensor versus angle of displacement of the moving vane.



Hall output voltage vs. position



AOA Vane and Mount with Hall Sensor



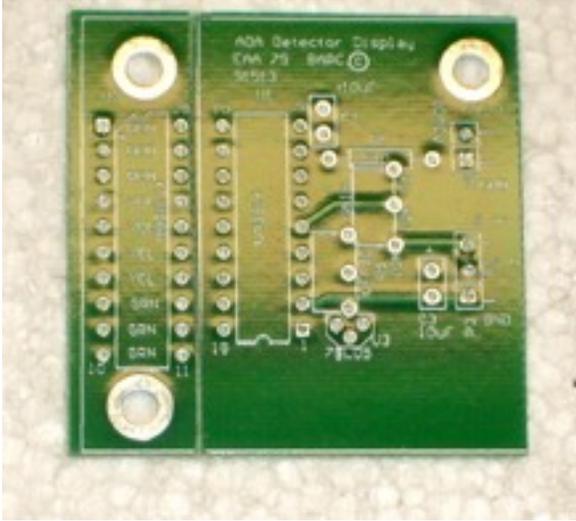
AOA Pitot Mount (Small hole holds Hall sensor)



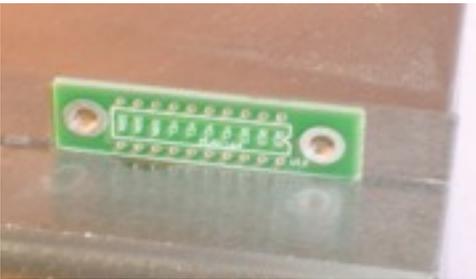
Board with cable and Hall sensor mounted off the side of PC board Note surface mount capacitor (Yellow cube) Note: pc board chage to single mount hole.



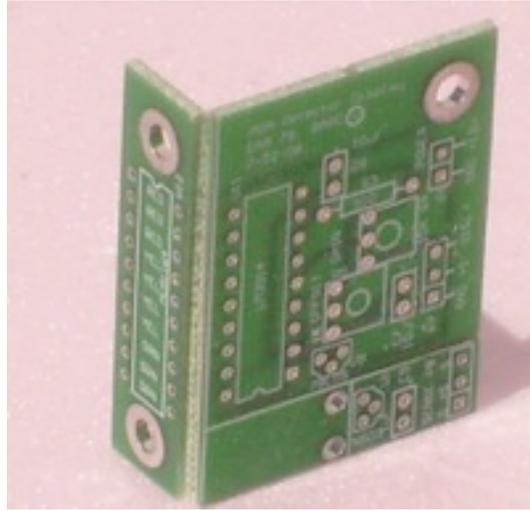
To minimize aircraft panel real estate, the top side of the PC board is scored about .030" deep (Red Line below) along the side of the bargraph display. Mount the bare board in a machine vice with the jaw edge along the score mark and bend the board



back against the sharp (square) edge. A mill vice is perfect for this operation.



Place in vice at the score line and Break scored line backwards for 90° fold



By carefully pushing the display portion backwards over the sharp edge of machine vise, the PC board folds the display portion 90° without breaking the connecting traces on the back surface. Hold it in the 90° position, and fill the gap with glue. If this is done carefully, you will not break any of the copper traces on the backside of the board. However, if you do damage a copper trace, scrape off the green solder mask on the broken trace, tin and bridge solder it with fine copper wire. The sensor portion of the circuit board is cut all the way through and can be broken out completely after the display section fold process.

Install the Hall device magnetic field sensor, plug and surface mount capacitor. This PC board is mounted on the Delrin ring sleeve support, which in turn carries the moving vane equipped with its permanent magnet. The magnet moves across the face of the Hall sensor as the aircraft pitches up and down.

Assembly

Populate the board with the components as shown on the board annotation and the photos. Make sure you have the proper part orientation before soldering the parts in place. Note: (Pin 1 of the HDSP-4822 LED display is noted by a beveled corner on its edge. The label will be on your left side) This will orient to the upper left corner of the PC board. The LM3914 driver chip orients its pin 1 downward bottom right direction.(notch) Additionally bridge soldering the touching display and driver chip leads that touch at the board fold will provide additional structural strength. Install Hall sensor cantilevered off its PC board ~ 3/8" Hall sensor should be flush with the AOA Mount surface.



AOA Vane Mounted next to Pitot tube (prototype) lock with 4-40 set screw.

Note: Connector has been deleted. Solder cable to the board

The most tedious portion of the job is usually the routing of the connecting cable (two conductor plus shield) Radio Shack p/n 278-513 from the sensor thru the wing to the aircraft instrument panel.

Calibration

The display board has two blue adjusting trim pots that allow scaling to fit the aircraft performance. Bend the leads 90 degree and mount these pots on edge. They should be glued as well as soldered to the PC board.

offset position. This Pot scaling adjustment will vary if you are flying a trike or a jet.

will vary if you are flying a trike or a jet. The uppermost trim pot on the display board sets the gain. I.e. How many bars the display moves up and down with each degree of vane rotation. The lower trim pot is an offset adjustment. This moves the span position (bottom green display element turn ON). This bottom, (or second from the bottom) Green LED should be ON when the aircraft is in straight and level flight. The upper RED light should turn on at the stall angle for your particular aircraft and wing design. A peak range of somewhere between 15°– 40° for most aircraft types.

Note: In ground calibration you will be pitching the vane downward to set the gain trim pot. Which is the same as the wing pitching upward while the vane maintains a constant position to the relative wind. Please note the gain and offset pots are somewhat interactive and will require some iteration to zero in on optimum.

Finally, **Please, Please if you are going to check out the limits of performance of your aircraft. Do it with lots of altitude!!!!** This device is an indicator. It will not rescue you from sloppy pilotage!
Dave Barker -copyright 3/06 revised 12/13

The AOA kit consists of:

Electronic components

Double sided PC Display boards
Cut and scored
SS49 Hall magnetic sensor *
*(Change of component since SA article)
LM 78L05 +5V Regulator
LM 3914 Bargraph Drive
MV5A164 Multicolor LED Display
10K Pot Bourns 842CO- R-103 (2)
510 ohm resistor
1uF Capacitor (surface mount)
10uF Capacitor
~ 1" Teflon Sleeve for hall sensor leads.(Trim to size as required)
3 pin plugs (1) PC board mount
2-pin plug (1) PC board mount
Cable termination connectors. (1)
Power terminal 2 pos Cable mount
Sensor Cable 3 Position Cable mount receptacle contacts (5)

Mechanical parts

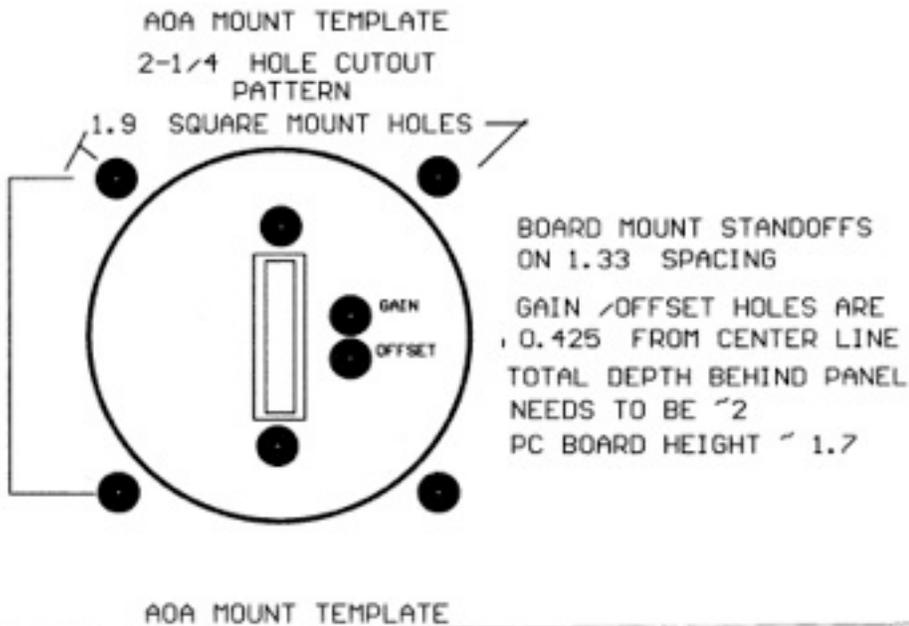
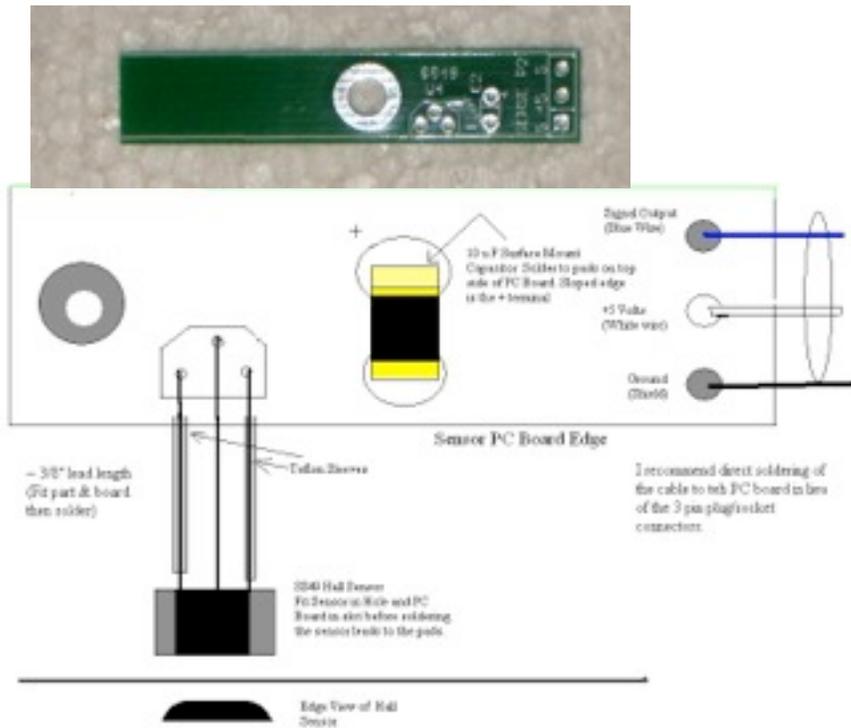
1/4" x 4-40 swage type standoff (2)
Delrin Sensor vane and fin
Post axle components
4-40 x 3/4" SHCS
0.55" x 5/16" brass sleeve
Magnet
0.374" x 0.1" dia. NdFeB
(White end goes up)
Vane
Delrin Pitot tube Mount Assembly
5" x 1/2" Delrin Vane
Aluminum, fin blank
You will also need 2 wire + shield mike cable Radio Shack p/n 278-513
(I do not provide this because it sets off alarms in the post office)

To order

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Top, Bottom & Overlay
PC board layout
(Old board)

- 4) **Mount Standoffs** I chucked a 1/4" transfer punch in my drill press and used it as an Arbor press to swage the 4-40 standoff mounts into the face of the display board. Trim off excess length of the PC board on the sensor board.



- 5) **Panel A** reference layout for the display for a 2-1/4" panel mount is attached.

- 6) **Vane Fin** Cut the .025" Aluminum fin stock to shape . Use some gel type crazy glue in the vane slot and press the fin into the slot with a vice.



(Peel protective film off the metal surface)

Fin Template

- 7) **Magnet** .Mount the NdFeB magnet in the slot on the inboard side of the Delrin vane. The Delrin does not glue too well . (I have had my best results with hot glue) Orient the magnet with the painted tip up. At the straight and level flight position, the magnet will be tilted backward $\sim 45^\circ$.
- 8)
- 9) **Pivot.** Use the 5/32" brass sleeve and the 4-40 x 3/4" socket head cap screw as a pivot for the vane. Use Loctite on threads. Take care not to get any Loctite between the brass sleeve exterior and the Delrin pivot hole.

AOA Vane (without fin), magnet and bearing sleeve
(preferred version is to not use 3 pin plug but solder cable directly to PC board.) Some conformal epoxy around the magnet can help hold and streamline the protruding magnet .

- 10) There is a **part change** on the Hall sense board. The 1 uF cap has be changed from a radial lead part to a surface mount part. This part is very tiny. Handle with tweezers and a magnifier and solder to the capacitor location on the board. The Plus + end of the part has the chamfered or marked edge. Straddle and then re-flow solder to the topside pads for the capacitor. Take care not to short the pads. This surface mount part is more difficult to work with but has less wind/vibration issues for this application. A good magnifier and steady hand are very helpful here.



- 11) **Mount the Hall sense** board in the slot on the AOA mount provided. The curve faces of the Hall sensor should be outboard and flush with the surface of the AOA mount structure. Back fill sensor mount hole with glue leaving the sensor face flush with the mount surface. Screw mount or glue as desired to the AOA mount structure. . The board can be conformal coated with a variety of polystyrene dopes or Krylon clear coats for weather protection. Check for rotation clearance. (near zero, but not dragging) as the magnet rotates past the hall sensor face.

- 12) **Finally** Check all wiring and PC boards for cold solder joints. **Correct parts orientation** and polarity. Clean up the solder flux with alcohol . Turn the gain pot to mid range and power up the unit and do some movement tests to assure operation. Start with the lower offset pot full CCW and adjust the gain pot for span (angle versus display movement. The offset pot can be adjusted to get the bottom (second from the bottom) GREEN light at straight and level flight orientation. The Gain pot should be adjust to the top RED for deep stall vane position. As the vane tips downward the bargraph should move up the scale.

